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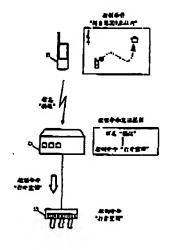
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权利要求书 5 页 说明书 23 页 附图页数 20 页

### [54]发明名称 移动体经端、自动遥控系统以及自动遥控 方法

#### [57]接任

本发明的移动体终端 31 检测出移动体终端的位置 及速度、方向并且根据 检测出的位置及速度、方向判定 控制条件。移动体终端 31 根据判定结果、将 湍足条件 的控制条件所对应的信息发送给控制终端 33。控制终 灣 33 根据接收 到的信息判定信息条件。控制终端 33 按其判定结果,将谓足条件的信息条件 所对应的控制命 令发送给对应的控制对象设备34。控制对象设备34执 行接收 到的控制命令。



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## MUBILE JERMINAL, AND AUJUMAILC REMUTE CONTROL STRIEM AND AUTOMATIC REMOTE CONTROL METHOD

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Inventor:

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Applicant: Classification: MATSUSHITA ELECTRIC IND CO LTD

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H04M11/00; H04Q7/34

- European:

H04M3/42M

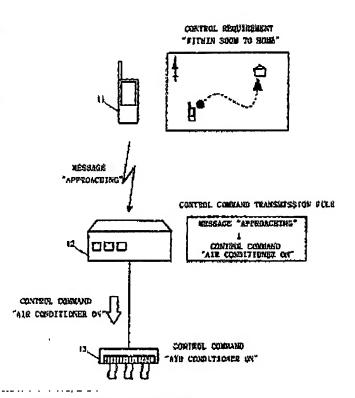
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#### Abstract of JP2002186053

PROBLEM TO BE SOLVED: To provide a mobile system that can automatically control a mobile terminal without the need for an operation of a user depending on a position, a speed and a direction of a mobile terminal and to provide the mobile terminal. SOLUTION: The mobile terminal 1 detects a position, a speed and a direction of itself to discriminate a control condition on the basis of the detected position, speed and direction. The mobile terminal 1 transmits a message corresponding to the control condition satisfying the discrimination result to a control terminal 2. The control terminal 2 discriminates a message condition on the basis of the received message. The control terminal 2 transmits a control command corresponding to the message condition satisfying the discrimination result to a corresponding control object device 3. The control object device 3 executes the control command according to the received control command.



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